Approximate Matrix Rank

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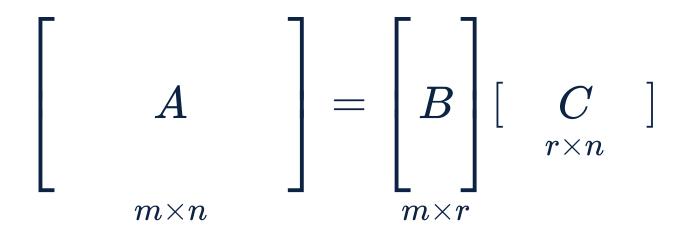


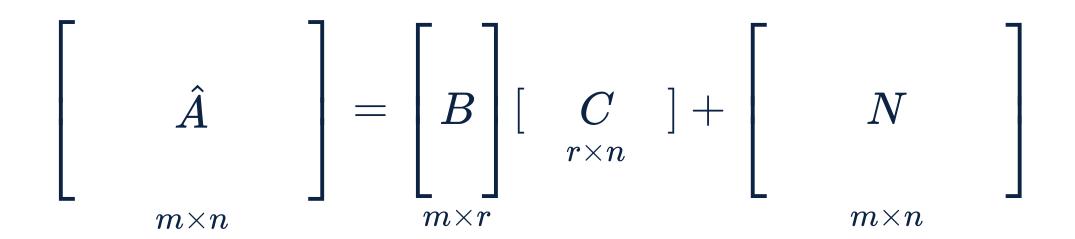
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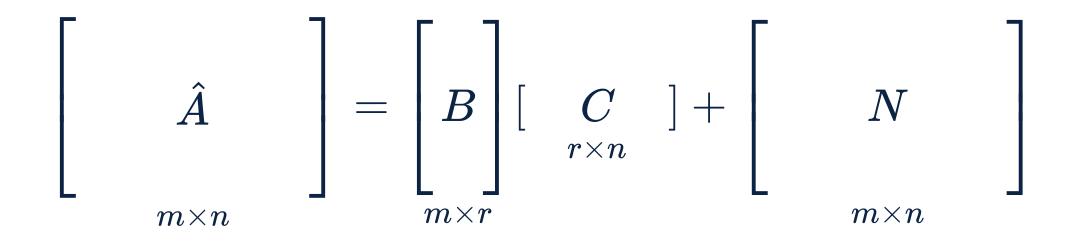
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- If the rank *r* is small, can greatly compress data:

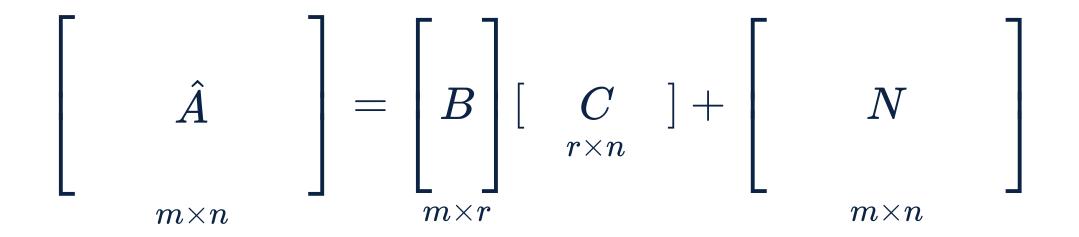




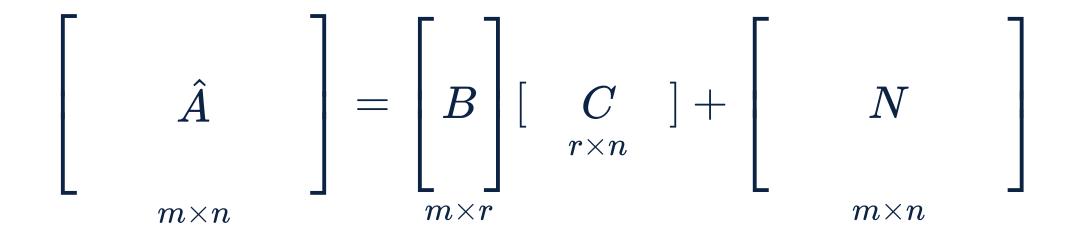
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- Don't know the number of features in your data 🙁



$$\mathrm{rank}_arepsilon(A) = \min_{\|E\| \leq arepsilon} \mathrm{rank}(A+E)$$

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- A.K.A. numerical or approximate rank

1. Vershynin (2018)

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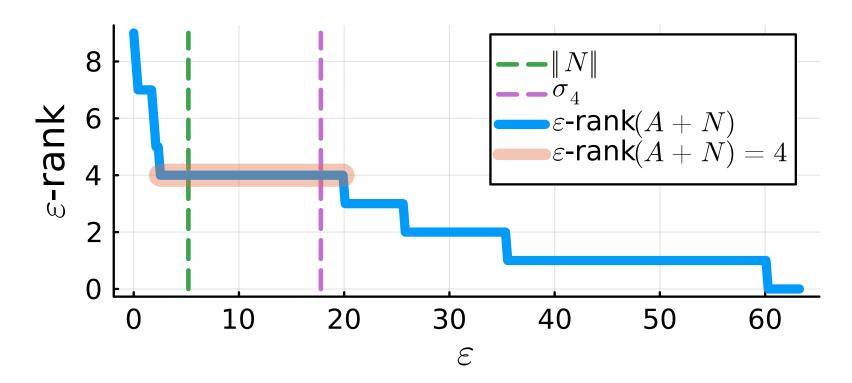
 $\operatorname{rank}_{\operatorname{\varepsilon}}(A+N)=\operatorname{rank}(A).$

- σ_r is the smallest nonzero singular value of A
- ε needs to be between the noise level ||N|| and the smallest important data (σ_r)
- Estimate standard Gaussian¹ $\|N\| \approx \sqrt{m} + \sqrt{n}$

• Generate random 9×9 rank-4 matrix A

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Future Work & References

Golub, Gene H., Virginia Klema, and Gilbert W. Stewart. 1977. "Rosetak Document 4: Rank Degeneracies and Least Square Problems." SSRN Scholarly Paper. Rochester, NY.

Vershynin, Roman. 2018. *High-Dimensional Probability*. Cambridge Series in Statistical and Probabilistic Mathematics. University of California, Irvine: Cambridge University Press.

Future Work & References

• How to pick the right ε ?

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Future Work & References

- How to pick the right ε ?
- What if A and A + N are nonnegative?

Golub, Gene H., Virginia Klema, and Gilbert W. Stewart. 1977. "Rosetak Document 4: Rank Degeneracies and Least Square Problems." SSRN Scholarly Paper. Rochester, NY.

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